

Dynamic prognostic tools using joint models for recurrent and terminal events: *Evolution after a breast cancer*

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Introduction

- **After a breast cancer diagnosis**
 - single or multiple events
(recurrences, metastases, death)

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- **Prediction of death**
 - clinical therapeutic decisions, and patient monitoring
 - patient information
 - trials : defining patient subpopulations

Introduction

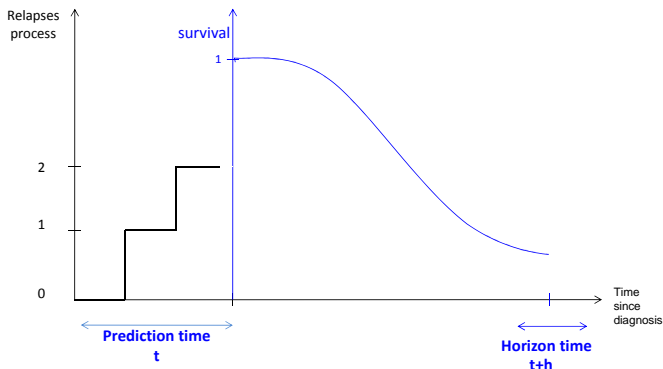
- **After a breast cancer diagnosis**
 - single or multiple events (recurrences, metastases, death)
- **Prediction of death**
 - clinical therapeutic decisions, and patient monitoring
 - patient information
 - trials : defining patient subpopulations
- **Account for**
 - individual characteristics
 - tumor characteristics
 - previous treatments
 - evolution of longitudinal markers (*Rizopoulos, 2011 ; Proust-Lima 2009*)

Introduction : Motivating example

- Cohort of patients with **operable breast cancer**
- Treated in a **comprehensive cancer center** and followed 13.9 years (median)
- **Recurrent events** observed : loco-regional relapses, distant metastases ; until 3 events per patient
- Hypothesis : individual covariates but also **recurrent event process** may improve prediction of death risk

Objective

To predict the risk of death between time t and $t + h$ given the recurrent event process before time t in the context of joint modeling



Joint Models

- Recurrent events and death **processes** are potentially **correlated**
- Standard (naive) approach of Cox with time-dependent covariate only for **external covariates** !
- Interest :
 - investigating the **strength of association** between recurrent events and death
 - allows to study impact of **covariates both** on recurrent events and death
 - treat **informative censoring** by death

Joint models : some notations

- t time of prediction and h window of prediction
- D_i time of death for subject i , $i = 1, \dots, n$
- X_{ij} time of the j th recurrence for subject i
- Z_{ij}^R and Z_i^D covariates vectors for recurrence and death
- λ_{ij}^R and λ_i^D baseline hazards for risk of recurrence or death

Joint models

Joint modeling for the risk of recurrent event (disease relapses) and terminal event (death)

$$\begin{cases} \lambda_{ij}^R(t|u_i) = u_i \lambda_0^R(t) \exp(\beta_1' Z_{ij}^R) \\ \lambda_i^D(t|u_i) = u_i^\alpha \lambda_0^D(t) \exp(\beta_2' Z_i^D) \end{cases}$$

- calendar timescale (time from origin)
- $u_i \sim \Gamma(1/\theta; 1/\theta)$, i.e. $E(u_i) = 1$ and $\text{var}(u_i) = \theta$
- θ dependency between recurrent events and death
- α sense and strength of the association (more flexibility)

Liu et al. Biometrics 2004 ; Rondeau et al. Biostatistics 2007

Inference in the joint model

Penalized log-likelihood :

- smooth baseline hazard functions
- approximated by cubic M-splines

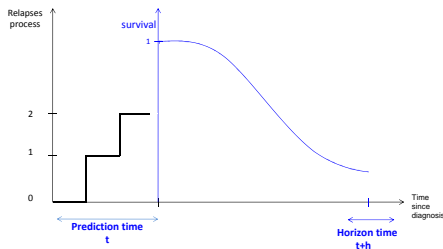
$$pl(\xi) = l(\xi) - \kappa_1 \int_0^\infty (\lambda_0^R(t))''^2 dt - \kappa_2 \int_0^\infty (\lambda_0^D(t))''^2 dt$$

With the vector of parameters : $\zeta = (\lambda_0^D(.), \lambda_0^R(.), \beta, \alpha, \theta)$
and κ_1 and κ_2 two smoothing parameters for the baseline hazard functions

Dynamic prediction

- Consider a new subject i **free of death at time t** (i.e. $D > t$), for whom we observe j recurrences before t and for whom the vector of covariates Z_{ij}^R and Z_{ij}^D are available at time of prediction
- The history of recurrences for patient i until time t is :

$$\mathcal{H}_i^j(t) = \{N_i^R(t) = J, X_{i1} < \dots < X_{iJ} \leq t\}$$



Dynamic prediction

Distinguish **three setting** for the probability of death between t and $t + h$

Setting 1

Exactly 3 recurrent events before t



Setting 2

At least 3 recurrent events before t



Setting 3

Whatever the history of recurrent events before t



× Recurrent event

— Period where we consider what happens

■ Window of prediction of death

--- Period where we do not consider what happens

Dynamic prediction

Setting 1 : with exactly j recurrences before t

$$P^1(t, t+h; \xi) = P(D_i \leq t+h | D_i > t, \mathcal{H}_i^{J,1}(t), Z_{ij}^R, Z_i^D, \xi)$$

$$= \frac{\int_0^\infty [S_i^D(t|Z_i^D, u_i, \xi) - S_i^D(t+h|Z_i^D, u_i, \xi)] (u_i)^J S_{i(J+1)}^R(t|Z_{ij}^R, u_i, \xi) g(u_i) du_i}{\int_0^\infty S_i^D(t|Z_i^D, u_i, \xi) (u_i)^J S_{i(J+1)}^R(t|Z_{ij}^R, u_i, \xi) g(u_i) du_i}$$

and $\mathcal{H}_i^{J,1}(t) = \{N_i^R(t) = J, X_{i1} < \dots < X_{iJ} \leq t\}$, with $X_{i0} = 0$ and $X_{i(J+1)} > t$

Dynamic prediction

Setting 1 : with exactly j recurrences before t

$$P^1(t, t+h; \xi) = P(D_i \leq t+h | D_i > t, \mathcal{H}_i^{J,1}(t), Z_{ij}^R, Z_i^D, \xi)$$

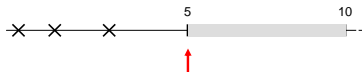
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and $\mathcal{H}_i^{J,1}(t) = \{N_i^R(t) = J, X_{i1} < \dots < X_{iJ} \leq t\}$, with $X_{i0} = 0$ and $X_{i(J+1)} > t$

Example :

"Up to now Mr Martin has developed 3 recurrences of his initial cancer, his probability of dying in the next 5 years is $x\%$ "

Exactly 3 recurrent events before t



Dynamic prediction

Setting 2 : with at least j recurrences before t

$$P^2(t, t+h; \xi)$$

$$= \frac{\int_0^\infty [S_i^D(t|Z_i^D, u_i, \xi) - S_i^D(t+h|Z_i^D, u_i, \xi)] (u_i)^J S_{ij}^R(X_{ij}/Z_{ij}^R, \xi, u_i) g(u_i) du_i}{\int_0^\infty S_i^D(t|Z_i^D, \xi, u_i) (u_i)^J S_{ij}^R(X_{ij}/Z_{ij}^R, \xi, u_i) g(u_i) du_i}$$

and $\mathcal{H}_i^{J,2}(t) = \{N_i^R(t) \geq J, X_{i1} < \dots < X_{ij} \leq t\}$, with $X_{i0} = 0$

Dynamic prediction

Setting 2 : with at least j recurrences before t

$$P^2(t, t+h; \xi)$$

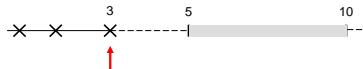
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and $\mathcal{H}_i^{J,2}(t) = \{N_i^R(t) \geq J, X_{i1} < \dots < X_{ij} \leq t\}$, with $X_{i0} = 0$

Example :

"Mr Martin has already developed 3 recurrences, if he is still alive in 2 years, his probability of dying between 5 and 10 years will be x% "

At least 3 recurrent events before t



Dynamic prediction

Setting 3 : considering the recurrence history only in the parameters estimation

$$\begin{aligned}
 & P^3(t, t+h; \xi) \\
 &= P(D_i \leq t+h | D_i > t, Z_i^D, \xi) \\
 &= \frac{\int_0^\infty [S_i^D(t | Z_i^D, u_i, \xi) - S_i^D(t+h | Z_i^D, u_i, \xi)] g(u_i) du_i}{\int_0^\infty S_i^D(t | Z_i^D, \xi, u_i) g(u_i) du_i}
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Dynamic prediction

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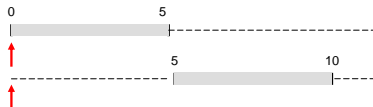
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 \end{aligned}$$

Example :

" his probability of dying in the next 5 years is x%"

" if his still alive in 5 years, his probability of dying over the next 5 years will be x%"

Whatever the history of recurrent events before t



Dynamic prediction : variability of the probability estimators

by **Monte Carlo** :

- at each b step ($b=1, \dots, B=1000$) :
 $\hat{\xi} = (\widehat{\lambda_0^R(\cdot)}, \widehat{\lambda_0^D(\cdot)}, \hat{\beta}, \hat{\alpha}, \hat{\theta})$ from $\mathcal{MN}(\hat{\xi}, \hat{\Sigma}_{\xi})$.
 estimate $P^b(t, t+h; \hat{\xi})$
- Percentile confidence interval : using the 2.5th and the 97.5th percentiles

Dynamic prediction : Error of prediction

Based on a **weighted time-dependent Brier Score**
(IPCW error)

$$Err_{t+h} = \frac{1}{N_t} \sum_{i=1}^{N_t} [I(T_i^D > t+h) - (1 - \hat{P}(t, t+h; \hat{\xi}))]^2 \hat{w}_i(t+h, \hat{G}_N(.))$$

with

$$w_i(t+h, \hat{G}_N(.)) = \frac{I(T_i^D \leq t+h) \delta_i^D}{\hat{G}_N(T_i^D) / \hat{G}_N(t)} + \frac{I(T_i^D > t+h)}{\hat{G}_N(t+h) / \hat{G}_N(t)}$$

T_i^D = observed survival time ; δ_i = event indicator

N_t = patients alive and uncensored at t

$\hat{G}_N(t)$ = KM estimate or adjusted Cox estimate of the censoring distribution

Validated by a 10-fold cross-validation

Brier. Monthly Weather Review 1950 - Gerds et al. Biometrical J 2006

Application

- 1067 patients
- median follow-up : 13.8 years (min=5 months)
- 330 patients died
- 362 patients with recurrent events (mean 0.40), i.e. 427 observations (locoregional relapses and distant metastases)

N events	0	1	2	3
Alive	600	114	20	3
Died	105	187	37	1
All	705	301	57	4

with the R package **frailtypack** :

(<http://cran.r-project.org/web/packages/frailtypack/>)

Prognostic joint model

Variable	% of patients	For recurrent events		For death	
		HR	(95% CI)	HR	(95% CI)
- Age					
[40 – 55] vs [55 – 84]	(36.6)	1.18	(0.92-1.51)	0.36	(0.19-0.66)
[28 – 40] vs [55 – 84]	(7.7)	2.54	(1.82-3.56)	1.76	(0.82-3.81)
- P. vasc. invas.	(26.7)	1.47	(1.15-1.88)	3.35	(1.80-6.25)
- Tumor size	(22.7)	1.86	(1.47-2.37)	4.68	(2.70-8.12)
> 20 vs ≤ 20 mm					
- HER2 positive	(11.2)	1.43	(1.03-1.99)	1.31	(0.62-2.77)
- HR	(83.0)	0.81	(0.57-1.16)	0.23	(0.10-0.54)
(+ vs -)					
- Nodes involv.	(42.3)	1.82	(1.42-2.32)	4.52	(2.43-8.41)
(yes vs no)					
- Grade					
II vs I	(45.7)	2.14	(1.55-2.95)	7.99	(3.39-18.85)
III vs I	(24.6)	2.21	(1.48-3.31)	10.80	(4.13-33.76)
θ			1.04 (se=0.06)		
α			4.61 (se=0.28)		
LCV			2.04		

Prediction values - between 5 and 10 years

Recurrence history	Risk of death between 5 and 10 years		
	$P^1(5, 10; \hat{\xi})$	$P^2(5, 10; \hat{\xi})$	$P^3(5, 10; \hat{\xi})$
No recurrence	10.8 (4.2)	10.8 (4.2)	12.7 (4.5)
One recurrence			
$X_{i1} = 1$	30.3 (8.9)	33.3 (8.9)	12.7 (4.5)
$X_{i1} = 2.5$	30.3 (8.9)	32.3 (8.9)	12.7 (4.5)
$X_{i1} = 4.9$	30.3 (8.9)	30.4 (8.9)	12.7 (4.5)
Two recurrences			
$X_{i1} = 1, X_{i2} = 2$	50.6 (11.4)	53.2 (11.1)	12.7 (4.5)
$X_{i1} = 2, X_{i2} = 4$	50.6 (11.4)	51.5 (11.3)	12.7 (4.5)
$X_{i1} = 4, X_{i2} = 4.9$	50.6 (11.4)	50.7 (11.4)	12.7 (4.5)
Three recurrences			
$X_{i1} = 1, X_{i2} = 2, X_{i3} = 3$	67.4 (11.9)	68.9 (11.4)	12.7 (4.5)
$X_{i1} = 1, X_{i2} = 2.5, X_{i3} = 4.9$	67.4 (11.9)	67.5 (11.9)	12.7 (4.5)
$X_{i1} = 3, X_{i2} = 4, X_{i3} = 4.9$	67.4 (11.9)	67.5 (11.9)	12.7 (4.5)

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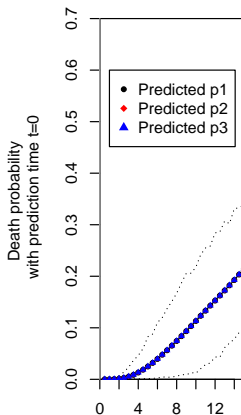
Prediction values - between 5 and 15 years

Recurrence history	Risk of death between 5 and 15 years		
	$P^1(5, 15; \hat{\xi})$	$P^2(5, 15; \hat{\xi})$	$P^3(5, 15; \hat{\xi})$
No recurrence	22.7 (4.8)	22.7 (4.8)	25.6 (4.7)
One recurrence			
$X_{i1} = 1$	53.0 (6.9)	56.2 (6.3)	25.6 (4.7)
$X_{i1} = 2.5$	53.0 (6.9)	55.2 (6.5)	25.6 (4.7)
$X_{i1} = 4.9$	53.0 (6.9)	53.1 (6.9)	25.6 (4.7)
Two recurrences			
$X_{i1} = 1, X_{i2} = 2$	75.6 (6.0)	77.5 (5.4)	25.6 (4.7)
$X_{i1} = 2, X_{i2} = 4$	75.6 (6.0)	76.3 (5.8)	25.6 (4.7)
$X_{i1} = 4, X_{i2} = 4.9$	75.6 (6.0)	75.6 (6.0)	25.6 (4.7)
Three recurrences			
$X_{i1} = 1, X_{i2} = 2, X_{i3} = 3$	88.4 (4.1)	89.2 (3.7)	25.6 (4.7)
$X_{i1} = 1, X_{i2} = 2.5, X_{i3} = 4.9$	88.4 (4.1)	88.4 (4.1)	25.6 (4.7)
$X_{i1} = 3, X_{i2} = 4, X_{i3} = 4.9$	88.4 (4.1)	88.4 (4.1)	25.6 (4.7)

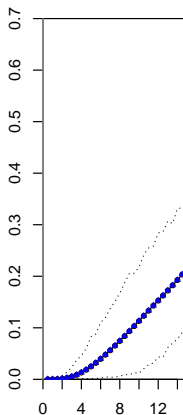
Death prediction for 2 particular cases

Baseline prediction : between 40 and 55 years, no peritumoral vasc. invasion, tumor size ≤ 20 mm, HER2 -, RH +, no lymph node invol., grade II

Patient 1
With recurrences

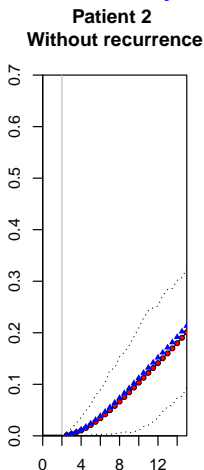
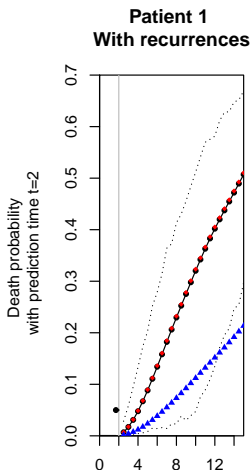


Patient 2
Without recurrence



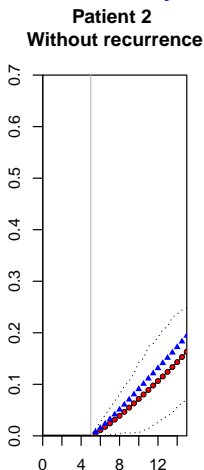
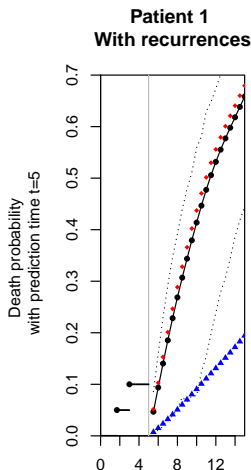
Death prediction for 2 particular cases

Prediction time $t=2$ years



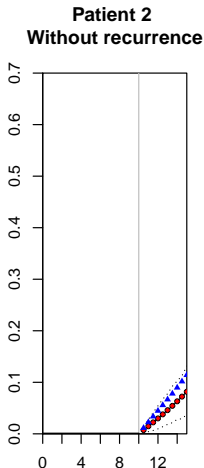
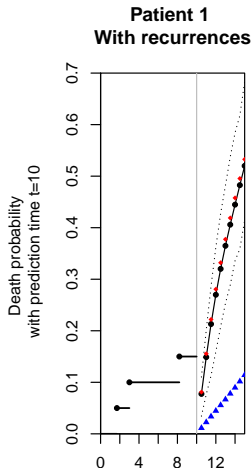
Death prediction for 2 particular cases

Prediction time $t=5$ years



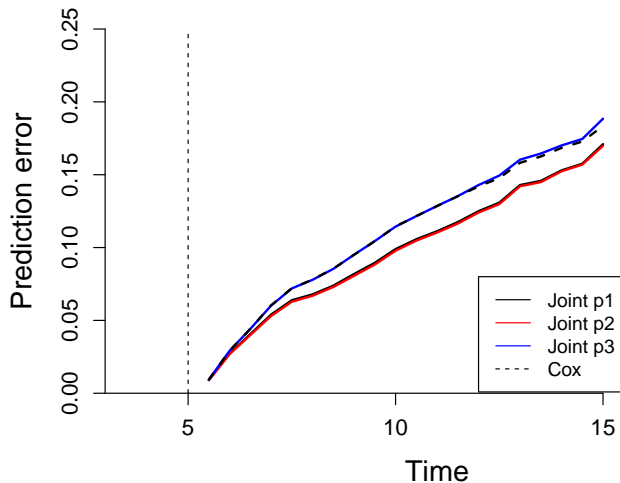
Death prediction for 2 particular cases

Prediction time $t=10$ years



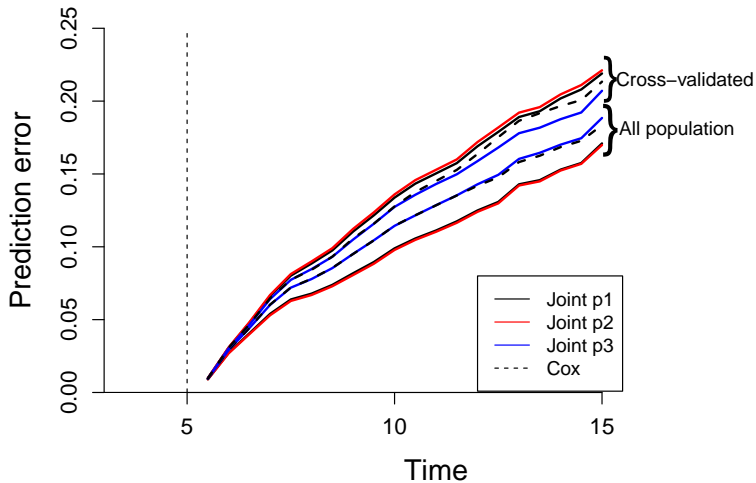
Death prediction error

Prediction at 5 years (949 patients alive)



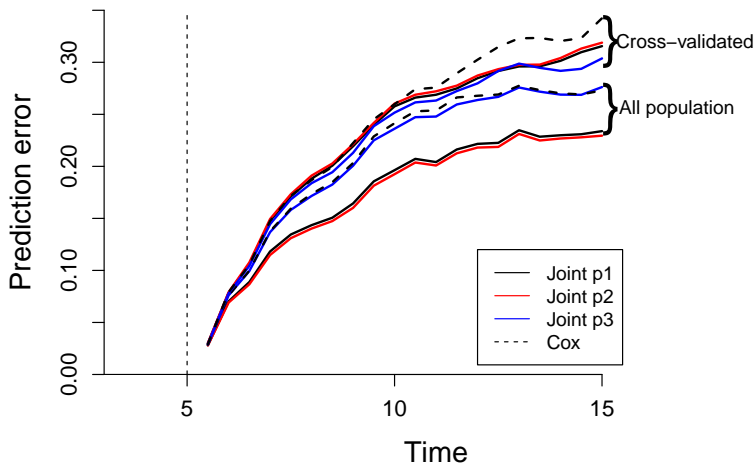
Prediction error

Prediction at 5 years (949 patients alive), with 10-fold cross-validation



Prediction error

Prediction at 5 years (267 patients alive with recurrence),
with 10-fold cross-validation



Conclusion

- **Recurrent event process** seems interesting to predict the risk of death, in framework of joint models
- **Dynamic prediction** : updated with new events
- Joint modeling gives **better results** than Cox model with lower **prediction error**
- However, the 10-fold cross-validation suggests a higher risk of **over-fitting**
- **Conditional prediction** possible, but interest is limited
- Perspective :
 - Independent **external validation** (See A. Mauguen poster)
 - To study the prediction of the **risk of events** along with the risk of death
 - Prediction using **alternative models** ?

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