# The Landmark Approach: An Introduction and Application to Dynamic Prediction in Competing Risks 

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## Outline

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Dynamic prediction
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## Landmarking

Origin of landmarking

- Origin: debate on the effect of response to chemotherapy on survival (Anderson JR, Cain KC, Gelber RD, 1983, J Clin Oncol 1, 710-719)
- Common way of analysis: make two groups, a "responder" group and a "non-responder" group and compare survival between these two groups
- Problem with this approach: a potential responder will only belong to the "responder" group if he/she survives until time of response
- Individuals in the responder group are immortal for some time, this gives them an unfair survival advantage: immortal time bias


## Time-dependent covariates

- The problem comes in a number of disguises
- Effect of recurrence on survival in cancer
- Effect of transplant failure on survival in transplant studies
- Effect of compliance on recurrence
- Effect of drug-specific adverse events on recurrence
- Effect of winning an Oscar on survival for US actors (Ann Intern Med)
- Unfortunately the incorrect approach is still prevalent in medical journals


## Correct approaches

- Crucial issue: "responder" versus "non-responder" is something that is not known at baseline
- When studying survival, it is not allowed to make groups based on something that will happen in the future
- Two alternatives proposed
- Time-dependent covariate
- Landmark
- Consider response at fixed point in time (landmark)
- Remove patients with event (or censored) before landmark from analysis


## Dynamic prediction

- Prediction is often well known from start treatment/diagnosis/...
- Depends on patient characteristics known at baseline
- Patient comes back for regular (6 months eg) checks
- Baseline covariates have not changed
- But event history (clinical events) may have changed
- Biomarkers ...
- As a result, prognosis will have changed
- Also if patient has had no events
- Prediction needs to be updated (dynamic prediction)


## US Health and Retirement Study (HRS)

- HRS: number of nationally representative cohorts
- Here only oldest cohort (AHEAD) used, born before 1923, aged 70 and older in 1993
- Outcome of interest: overall survival; time scale is age
- Time-fixed covariates $Z$ at entry: gender, education, BMI, smoking
- Time-dependent covariate

$$
Z_{\mathrm{ADL}}(t)= \begin{cases}1, & \text { if subject is ADL-disabled at age } t ; \\ 0, & \text { otherwise. }\end{cases}
$$

- Basic Activities of Daily Living (walking, bathing, dressing, toileting, feeding), disabled if "with difficulty" for $\geq 1$ item


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- Basic Activities of Daily Living (walking, bathing, dressing, toileting, feeding), disabled if "with difficulty" for $\geq 1$ item
- Objective: dynamic prediction of survival of at least 10 years beyond age $s$, with given ADL-disability status at age $s$ and given covariates


## Covariates

| Covariate | N | $(\%)$ |
| :--- | ---: | ---: |
| Gender |  |  |
| $\quad$ Male | 1564 | $(39 \%)$ |
| $\quad$ Female | 2468 | $(61 \%)$ |
| Education |  |  |
| $\quad$ Less than high school | 1736 | $(43 \%)$ |
| High school | 1212 | $(30 \%)$ |
| $\quad$ Some college | 1084 | $(27 \%)$ |
| BMI |  |  |
| $\quad$ 25 | 2244 | $(56 \%)$ |
| $25-30$ | 1388 | $(34 \%)$ |
| $>30$ | 390 | $(10 \%)$ |
| Smoking |  |  |
| Never | 1997 | $(50 \%)$ |
| Past | 1683 | $(42 \%)$ |
| Current | 324 | $(8 \%)$ |

## Multi-state approach

- Multi-state model; process $X(t)$ in time, taking values
- 0: alive without ADL disability
- 1: alive with ADL disability
- 2: dead

- Reversible illness-death model


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- Reversible illness-death model
- Objective: estimation of $P\left(X(s+w)<2 \mid X(s)=0, Z^{*}\right)$ and L $P\left(X(s+w)<2 \mid X(s)=1, Z^{*}\right)$ for given $Z^{*}$


## Estimated transition hazards



## Dynamic prediction for the multi-state model <br> If the Markov assumption holds

- There are no easy closed-form expressions for the prediction probabilities (because the multi-state model is reversible)
- The Aalen-Johansen estimator can be used to obtain estimates of prediction probabilities but is laborious
- Implemented in mstate


## Otherwise

- If the Markov assumption does not hold, we would have to use (micro-)simulation
- In our data, there is evidence that history of ADL-disability LU increases disability rate ( $\Rightarrow$ violation of Markov assumption) MC


## Dynamic prediction and landmarking

- Idea to use landmarking for dynamic prediction stems from van Houwelingen (2007)
- Suppose we want to estimate the probability, given alive at age 80, of survival until age 90


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- Suppose that we had an enormous database at our disposal
- We would select a subset of the data, consisting of everyone alive at age 80


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- And simply count how many are alive at age 90 and calculate proportion


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- Suppose that we had an enormous database at our disposal
- We would select a subset of the data, consisting of everyone alive at age 80 (a landmark data set)
- And simply count how many are alive at age 90 and calculate proportion
- If there is censoring, we would estimate the probability using Kaplan-Meier
- If there are also covariates involved, we could incorporate them in a Cox model


## Landmarking in general terms

For each of a set of landmark time points $s \in\left[s_{0}, s_{1}\right]$

- Construct corresponding landmark data set, by selecting all individuals at risk at $s$
- Define $Z(s)$ : current vector of predictors, including intermediate events (depends on landmarking time point $s$ )
- Fit simple Cox model

$$
\lambda(t \mid Z(s), s)=\lambda_{0}(t \mid s) \exp \left(\beta(s)^{\top} Z(s)\right)
$$

for $s \leq t \leq t_{\text {hor }}$, enforcing administrative censoring at $t_{\text {hor }}$

- After having obtained estimates $\hat{\beta}(s)$ and $\hat{\Lambda}_{0}(t \mid s)$ :
- Estimate of prediction probability $P\left(T>t_{\text {hor }} \mid T>s, Z^{*}(s)\right)$ LU is then given by $\exp \left(-\exp \left(\hat{\beta}(s)^{\top} Z^{*}(s)\right) \hat{\Lambda}_{0}\left(t_{\text {hor }} \mid s\right)\right)$


## Robustness

- Note: for fixed $s$ and $t_{\text {hor }}$, the Cox model

$$
\lambda(t \mid Z(s), s)=\lambda_{0}(t \mid s) \exp \left(\beta(s)^{\top} Z(s)\right)
$$

uses $Z(s)$ as time-fixed covariates and $\beta(s)$ as time-fixed covariate effects

- Xu \& O'Quigley (2000) and van Houwelingen (2007): even if the effect of $Z(s)$ is time-varying, the above model give accurate (dynamic) predictions provided
- Administrative censoring is enforced at $t_{\text {hor }}$ during estimation of the Cox model
- Prediction is only used at $t_{\text {hor }}$


## Combining information

- Estimate parameters by fitting simple Cox model

$$
\lambda(t \mid Z(s), s)=\lambda_{0}(t \mid s) \exp \left(\beta(s)^{\top} Z(s)\right)
$$

for $s \leq t \leq t_{\text {hor }}$, enforcing administrative censoring at $t_{\text {hor }}$

- Can be done for each landmark point separately
- But we would expect the coefficients $\beta(s)$ to depend on $s$ in a smooth way
- Can use splines or parametric model, eg

$$
\beta(s)=\beta_{0}+\beta_{1} s
$$

## How to implement it

- Fitting this combined model can be done using standard software
- Stack the landmark data sets
- Stratify by landmark
- Estimated coefficients are correct, but for standard errors we need correction for the fact that data of the same patient are used repeatedly
- Sandwich estimators (Lin \& Wei, 1989)
- Baseline hazard estimated by Breslow estimator
- Depends on $s$ unless both $Z(s)$ and $\beta(s)$ are constant


## Baseline hazards

- Baseline hazards for different landmark time points s may be combined
- To add more structure and to make it easier to interpret the models
- We may assume a model

$$
\lambda_{0}(t \mid s)=\lambda_{0}(t) \exp (\theta(s))
$$

with $\theta\left(s_{0}\right)=0$ for identifiability

- In our application we take

$$
\theta(s)=\theta_{1} s+\theta_{2} s^{2}
$$

- Model can be fitted directly by applying a simple Cox model to the stacked data set
- Landmark time $s$ not used as stratifying variable but as covariate


## Set-up

- Endpoint is survival in a window of fixed width $w=10$ years from the moment of prediction
- Landmark time points used: 16 points, equally spaced, from age 75 to age 90
- For each landmark (prediction) time point, construct landmark data set, containing all relevant information needed for the prediction
- In all data sets we take all patients still at risk (alive), compute the current value of ADL-disability, and set the horizon at $t_{\text {hor }}=t_{\mathrm{LM}}+10$ years
- At each landmark point we fit a simple Cox model on ( $t_{\mathrm{LM}}, t_{\mathrm{hor}}$ ) and use that to obtain a prediction of survival at $t_{\text {hor }}+10$


## Landmarking in action

## The landmark data sets



LU MC

## Regression coefficients

## Regression coefficients with $95 \%$ confidence intervals



## Landmark super model

| Covariate | Category | B | SE |  |
| :--- | :--- | ---: | ---: | :---: |
| Gender | Female | -0.465 | 0.063 |  |
| Education | High school | -0.111 | 0.068 |  |
|  | College | -0.234 | 0.072 |  |
| BMI | $25-30$ | -0.344 | 0.065 |  |
|  | $>30$ | -0.135 | 0.098 |  |
| ADL | ADL disabled | 0.636 | 0.050 |  |
| Smoking | Past smoker | 0.389 | 0.166 |  |
|  | $\times \bar{s}$ | -1.020 | 0.586 |  |
|  | $\times \bar{s}^{2}$ | 0.739 | 0.506 |  |
|  | Current smoker | 1.024 | 0.205 |  |
|  | $\times \bar{s}$ | -1.460 | 0.810 |  |
|  | $\times \bar{s}^{2}$ | 0.538 | 0.794 |  |
| $\theta(s)$ | $\bar{s}$ | 0.971 | 0.424 |  |
|  | $\bar{s}^{2}$ | 0.021 | 0.356 |  |
| $\bar{s}=(s-75) / 15$ |  |  |  |  |

## With corresponding baselines




## Regression coefficients

Blue lines are the (landmark-varying) supermodel effect estimates


## Dynamic predictions from the landmark super model <br> Healthy <br> ADL disabled -- -



LU
MC

## Software

dynpred

- It is not so difficult to write your own code in the statistical package of your choice
- In R, package dynpred is available on CRAN (cran.r-project.org)
- The companion package of the book "Dynamic Prediction in Clinical Survival Analysis" by Hans van Houwelingen and myself (Chapman \& Hall)
- Functions available to create landmark data sets, applying administrative censoring at horizon (cutLM), and to calculate dynamic "death within window" curves (Fwindow)
- On the book website
http://www.msbi.nl/DynamicPrediction, R code (using the dynpred package) of all the analyses in the book is available for download


## Data (EBMT)

- 5582 CML patients with transplantation (SCT) between 1997 and 2003
- Two competing risks: "relapse" (Rel) and "non-relapse mortality" (NRM)

Cumulative incidences


## Events of interest

- Objective:
- To give prognosis of the disease/recovery process after SCT for a patient with a given post-transplant history
- Prediction to be based on covariates
- Baseline: year of SCT, risk score (low, medium, high)
- Time-dependent: Acute Graft-versus-Host-Disease (aGvHD)
- Low or high grade aGvHD



## Time-dependent covariates

- Define
$Z_{\text {low }}(t)=\mathbf{1}$ \{occurrence of low grade aGvHD before time $\left.t\right\}$
$Z_{\text {high }}(t)=\mathbf{1}\{$ occurrence of high grade aGvHD before time $t\}$


## Objective

- For a patient, alive without relapse at time s after SCT, with given covariates $Z^{*}(s)$, what is the probability that he/she will
- have had relapse before time $s+w$
- have died without relapse before time $s+w$
- In our application: $w$ is five years


## Competing risks: notation

- $J$ types of failure
- $\tilde{T}$ time of failure, $C$ censoring time, $T=\min (\tilde{T}, C)$
- $D$ : type of failure, $\Delta=D$ if failure occurred, 0 otherwise
- $Z(t)$ vector of covariates (possibly time-dependent)
- We observe $\left(T_{i}, \Delta_{i}, Z_{i}(\cdot)\right)$ for individual $i$
- Assume censoring is independent of ( $\tilde{T}, D)$ given covariates
- Cumulative incidences

$$
F_{j}(t \mid s)=P(T \leq t, D=j \mid T>s)
$$

## Landmarking and competing risks <br> Approach based on cause-specific hazards

- Select a number of landmark time points
- For landmark time point $s$
- Construct landmark data set, by selecting subjects at risk at $s$; denote by $\mathcal{D}_{s}$
- Define $Z(s)$ : current (at $s$ ) vector of predictors
- Fit Cox models on the cause-specific hazards

$$
\lambda_{j}(t \mid Z(s), s)=\lambda_{j 0}(t \mid s) \exp \left(\beta_{j}(s)^{\top} Z(s)\right)
$$

- Obtain estimates $\hat{\beta}_{j}(s)$ and $\hat{\lambda}_{j 0}(t \mid s)$
- For given (new) patient calculate patient-specific

$$
\hat{\lambda}_{j}\left(t \mid Z^{*}(s), s\right)=\hat{\lambda}_{j 0}(t \mid s) \exp \left(\hat{\beta}_{j}(s)^{\top} Z^{*}(s)\right)
$$

- Calculate

$$
\hat{F}_{j}\left(t \mid Z^{*}(s), s\right)=\int_{s}^{t} \hat{\lambda}_{j}\left(u \mid Z^{*}(s), s\right) \hat{S}\left(u-\mid Z^{*}(s), s\right) d u
$$

## Cause-specific hazards approach

- Cortese \& Andersen (2010) looked at fixed set of landmark time points and over the whole future
- No administrative censoring applied
- Nicolaie et al. (2012): interested in fixed width predictions
- To be obtained at a continuum of prediction time points
- Administrative censoring applied (robust against violations of proportional hazards)
- Super models, combining different landmark models in one, were used
- For both approaches
- Covariate effects are expressed in terms of the rates (cause-specific hazards), not directly on the risks (cumulative incidences)
- Fine-Gray type approach combined with landmarking
- Done in Cortese \& Andersen (2010) approach (straightforward, because no super models)
- Not directly for Nicolaie et al. (2012)


## Modeling: intuition from complete data

Fix cause of interest $j$ and fix $s$

- For individual $i$ within $\mathcal{D}_{s}$, the survivors at $s$, define

$$
Y_{i}=\mathbf{1}\left\{T_{i} \leq s+w, D_{i}=j\right\}
$$

- Expectation of $Y_{i}$ in $\mathcal{D}_{s}$ is $P\left(T_{i} \leq s+w, D_{i}=j \mid T_{i}>s\right)$
- General idea: specify a model for $\mu_{i}(\beta)=E\left(Y_{i} \mid T_{i}>s, Z_{i}\right)$
- For some link function $g$, postulate

$$
g\left(\mu_{i}(\beta)\right)=\beta_{0}(s)+\beta^{\top}(s) \mathbf{Z}_{i}(s)
$$

- Score equation from binomial likelihood

$$
\sum_{i=1}^{n_{s}} \frac{\partial \mu_{i}(\beta)}{\partial \beta} \cdot \frac{1}{\mu_{i}\left(1-\mu_{i}\right)} \cdot\left[y_{i}-\mu_{i}\right]=0
$$

## Obtaining dynamic predictions

- For a new patient with covariate vector $\mathbf{Z}^{*}$
- Estimate of $P\left(T \leq s+w, D=j \mid T>s, \mathbf{Z}^{*}(s)\right)$ is

$$
\widehat{F}_{j}\left(s+w \mid \mathbf{Z}^{*}(s), s\right)=g^{-1}\left(\widehat{\beta}_{0}(s)+\widehat{\beta}^{\top}(s) \mathbf{Z}^{*}(s)\right)
$$

- Its variance is estimated consistently by

$$
\left(\frac{\mathrm{d} g^{-1}(x)}{\mathrm{d} X}\right)_{\mid x=\widehat{\beta}} \widehat{\mathbf{Z}}^{*} \cdot\left(\mathbf{Z}^{*}\right)^{\top} \cdot \widehat{\operatorname{var}}(\widehat{\beta}) \cdot \mathbf{Z}^{*}
$$

(delta-method)

## Dynamic pseudo-observations

- Recall

$$
Y_{i}=\mathbf{1}\left\{T_{i} \leq s+w, D_{i}=j\right\}
$$

- Unfortunately, not available for censored patients !
- Define the dynamic pseudo-observation

$$
\hat{\theta}_{i s}=n_{s} \hat{F}_{j}(s+w \mid s)-\left(n_{s}-1\right) \hat{F}_{j}^{(-i)}(s+w \mid s)
$$

where

$$
\hat{F}_{j}(s+w \mid s)=\sum_{s<t_{i} \leq s+w} \frac{d_{i j}}{n_{i}} \cdot \hat{S}\left(t_{i}-\mid s\right)
$$

with

- $d_{i j}=$ no of cause $j$ events at $t_{i} ; n_{i}=$ no at risk at $t_{i}$

000000

## Properties of dynamic pseudo-observations

No censoring

$$
\hat{\theta}_{i s}=\mathbf{1}\left\{T_{i} \leq s+w, D_{i}=j\right\}
$$

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No censoring

$$
\hat{\theta}_{i s}=\mathbf{1}\left\{T_{i} \leq s+w, D_{i}=j\right\}
$$

## With censoring

- (P1) $\hat{\theta}_{\text {is }}$ is asymptotically independent of $\hat{\theta}_{\text {s }}$ for individuals $i \neq I$ as $n_{s} \rightarrow \infty$
- (P2) $\hat{\theta}_{\text {is }}$ is asymptotically independent of $\hat{\theta}_{l s^{\prime}}$ for individuals $i \neq l$ and landmark time points $s \neq s^{\prime}$ as $n_{s}, n_{s^{\prime}} \rightarrow \infty$
- (P3) $E\left[\hat{\theta}_{i s} \mid T_{i}>s, \mathbf{Z}_{i}\right]$ equals asymptotically its theoretical counterpart $\mathrm{E}\left[1\left\{T_{i} \leq s+w, D_{i}=j\right\} \mid T_{i}>s,, \mathbf{Z}_{i}\right]$ as $n_{s} \rightarrow \infty \mathrm{~L} \mathbf{U}$
(Follow more or less directly from results in Graw et al. (2009).) $\mathbf{M C}$


## Censored data

## Fixed $s$

- $Y_{i}=\mathbf{1}\left\{T_{i} \leq s+w, D_{i}=j\right\}, i \in \mathcal{D}_{s}$ not observed
- Retain score equations and replace $y_{i}$ by pseudo-observations $\hat{\theta}_{\text {is }}$
- The quasi-score equation is

$$
\sum_{i=1}^{n_{s}} \frac{\partial \mu_{i}(\beta)}{\partial \beta} \cdot \frac{1}{\mu_{i}\left(1-\mu_{i}\right)} \cdot\left[\hat{\theta}_{i s}-\mu_{i}\right]=0
$$

- Estimating equations are asymptotically unbiased ( $\Rightarrow$ asymptotic normality of $\hat{\beta}$ )
- Note: we calculate only one pseudo-observation per individual


## Obtaining dynamic predictions

- For a new patient with covariate vector $\mathbf{Z}^{*}$
- Estimate of $P\left(T \leq s+w, D=j \mid T>s, \mathbf{Z}^{*}(s)\right)$ is

$$
\widehat{F}_{j}\left(s+w \mid \mathbf{Z}^{*}(s), s\right)=g^{-1}\left(\widehat{\beta}_{0}(s)+\widehat{\beta}^{\top}(s) \mathbf{Z}^{*}(s)\right)
$$

- Its variance is estimated consistently by

$$
\left(\frac{\mathrm{d} g^{-1}(x)}{\mathrm{d} X}\right)_{\mid x=\widehat{\beta}} \widehat{\mathbf{Z}}^{*} \cdot\left(\mathbf{Z}^{*}\right)^{\top} \cdot \widehat{\operatorname{var}}(\widehat{\beta}) \cdot \mathbf{Z}^{*}
$$

(delta-method)

## Super models: setup

- Define a set of landmark time points $0 \leq s_{1}<\ldots<s_{K} \leq \tau$
- Construct the corresponding landmark data sets $\mathcal{D}_{k}:=\mathcal{D}_{S_{k}}$
- Define the dynamic pseudo-observation $\hat{\theta}_{i k}$ of individual $i$ at time $s_{k}+w$
- Note again: only one per subject per $s_{k}$ (namely at $s_{k}+w$ )
- Define

$$
\hat{\theta}_{i}=\left(\hat{\theta}_{i k}, k \in \mathcal{L}_{i}\right), \mathcal{L}_{i} \subset\{1, \ldots, K\}
$$

- Longitudinal vector $\hat{\theta}_{i}$ truncated by death (Kurland \& Heagerty 2005)


## Super models

- Define $\mu_{i k}=\mu_{i}\left(s_{k}\right)=P\left(T_{i} \leq s_{k}+w, D_{i}=j \mid T_{i}>s_{k}\right)$
- GLM

$$
g\left(\mu_{i k} \mid Z_{i}\left(s_{k}\right)\right)=\beta_{0}\left(s_{k}\right)+\beta^{\top}\left(s_{k}\right) Z_{i}\left(s_{k}\right)
$$

- Choose smooth model for $I^{\text {th }}$ component of $\beta(s)$

$$
\beta_{l}(s)=\beta_{l}^{\top} h_{l}(s) \quad \Rightarrow \quad \beta(s)=H(s) \beta
$$

- The quasi-score equation for regression parameter $\beta$ is

$$
U(\beta)=\sum_{i=1}^{n} U_{i}(\beta)=\sum_{i=1}^{n} \frac{\partial \mu_{i}(\beta)}{\partial \beta} \cdot V_{i}^{-1}\left(\widehat{\theta}_{i}-\mu_{i}\right)=0
$$

- Asymptotic unbiasedness of these estimation equations follows (only for independence working correlation!)


## Dynamic prediction in super models

- For a new patient with covariate vector $\mathbf{Z}^{*}$
- The estimate of $P\left(T \leq s+w, D=j \mid T>s, \mathbf{Z}^{*}(s)\right)$ is

$$
\widehat{F}_{j}\left(s+w \mid \mathbf{Z}^{*}, s\right)=g^{-1}\left(\widehat{\beta}_{0}(s)+\widehat{\beta}^{\top}(s) \mathbf{Z}^{*}(s)\right)
$$

with $\widehat{\beta}(s)=H(s) \hat{\beta}$

- Its variance is estimated consistently by

$$
\left(\frac{\mathrm{d} g^{-1}(x)}{\mathrm{d} x}\right)_{\mid x=(\widehat{\beta})^{\top} \mathbf{Z}^{*}}^{2} \cdot\left(\mathbf{Z}^{*}\right)^{\top} \cdot H(s) \cdot \widehat{\operatorname{var}}(\widehat{\beta}) \cdot H(s)^{\top} \cdot \mathbf{Z}^{*}
$$

## Scatter-plot



## Model

| Covariate | Relapse |  | NRM |  |
| :--- | ---: | ---: | ---: | ---: |
|  | $\widehat{\beta}$ | $\mathrm{SE}(\widehat{\beta})$ | $\widehat{\beta}$ | $\mathrm{SE}(\widehat{\beta})$ |
| Intercept | -1.160 | 0.027 | -1.156 | 0.029 |
| $\quad$ Constant | 0.839 | 0.126 | -3.603 | 0.165 |
| $s$ | -1.072 | 0.129 | 2.080 | 0.183 |
| $s^{2}$ |  |  |  |  |
| Year of transplantation | 0.530 | 0.126 | -0.591 | 0.125 |
| Constant | -1.165 | 0.657 | 1.604 | 0.718 |
| $s$ | 0.553 | 0.678 | -1.079 | 0.766 |
| $s^{2}$ |  |  |  |  |
| Risk score | 0.166 | 0.022 | 0.431 | 0.025 |
| Low risk | 0.725 | 0.039 | 0.880 | 0.042 |
| Medium risk |  |  |  |  |
| High risk | -0.490 | 0.030 | 0.168 | 0.102 |
| Low grade aGvHD |  |  | 2.032 | 0.461 |
| Constant |  |  | -1.738 | 0.436 |
| $s$ | -1.305 | 0.054 | 1.916 | 0.129 |
| $s^{2}$ |  |  | -0.416 | 0.579 |
| High grade aGvHD |  |  | -0.524 | 0.545 |
| $\quad$ Constant |  |  |  |  |
| $s$ |  |  |  |  |
| $s^{2}$ |  |  |  |  |

## Regression coefficients of EBMT risk score



## Regression coefficients of aGvHD

High grade aGvHD


## Dynamic pseudo-observations

## 5-yr prediction probabilities



## Discussion

- For each landmark time point $s_{k}$ we only use (need) dynamic pseudo-observations at one fixed horizon $\left(s_{k}+w\right)$
- No proportional hazards assumptions needed
- Gain in robustness
- But possible loss of efficiency
- Method is direct and straightforward to implement in GEE software (especially using the pseudo package)
- Correlation structure of dynamic pseudo-observations is ignored in the estimating equations of the super models


## Discussion (general)

## Advantages of standard approach

- It is standard
- There is software
- You gain biological understanding (hopefully) by modeling the effects of covariates on transitions


## Advantages of landmarking

- It is more direct; no need for complicated formulas for prediction
- Predictions obtained from multi-state model may be off the mark if assumptions are violated or if model fit is not good
- Sparse model (considerably fewer parameters than multi-state model)


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